



Python Emission Localisation and Quantification (pyELQ)

Improving methane emission localisation and quantification through open sourcing

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This presentation may contain certain forward-looking non-GAAP measures such as cash capital expenditure and divestments. We are unable to provide a reconciliation of these forward-looking non-GAAP measures to the most comparable GAAP financial measures because certain information needed to reconcile those non-GAAP measures to the most comparable GAAP financial measures is dependent on future events some of which are outside the control of Shell, such as oil and gas prices, interest rates and exchange rates. Moreover, estimating such GAAP measures with the required precision necessary to provide a meaningful reconciliation is extremely difficult and could not be accomplished without unreasonable effort. Non-GAAP measures in respect of future periods which cannot be reconciled to the most comparable GAAP financial measure are calculated in a manner which is consistent with the accounting policies applied in Shell plc’s consolidated financial statements.

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Agenda

- 01** Background
Why are methane emissions important?
- 02** Technical details
The mathematics behind the code
- 03** Open-sourcing
Why LFE
- 04** Q&A



Background

Why are methane emissions worth reducing?

Why Methane Matters

- Methane is a powerful greenhouse gas; its impact on climate change over 20 years is more than 80 times greater than CO₂.
- Reducing emissions of methane is considered one of the most effective near-term actions to keep the more ambitious 1.5° C goal of the Paris Agreement within reach.
- Worldwide initiatives are taken to reduce global methane emissions.
- Shell has a target to maintain methane emissions intensity below 0.2% and achieve near-zero methane emissions by 2030.
- Shell has committed to the voluntary reporting framework OGMP2.0 under the flag of the United Nations Environmental Programme, which aims to increase transparency and accuracy of methane emissions reporting.



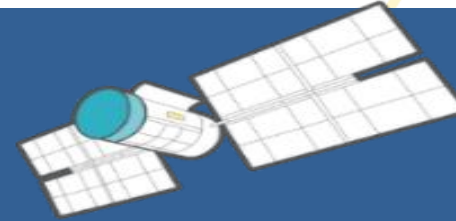
Some references

- [Homepage | Global Methane Pledge](#)
- [Global Methane Tracker 2024 - Analysis - IEA](#)
- [The Oil & Gas Methane Partnership 2.0 \(OGMP 2.0\) | UNEP - UN Environment Programme](#)
- [Home - Aiming For Zero \(ogci.com\)](#)
- [Reduce Global Methane Emissions | Methane Guiding Principles](#)
- [Shell.com Methane](#)

Overview of technologies for methane emission measurement



Source-level measurements



Satellites

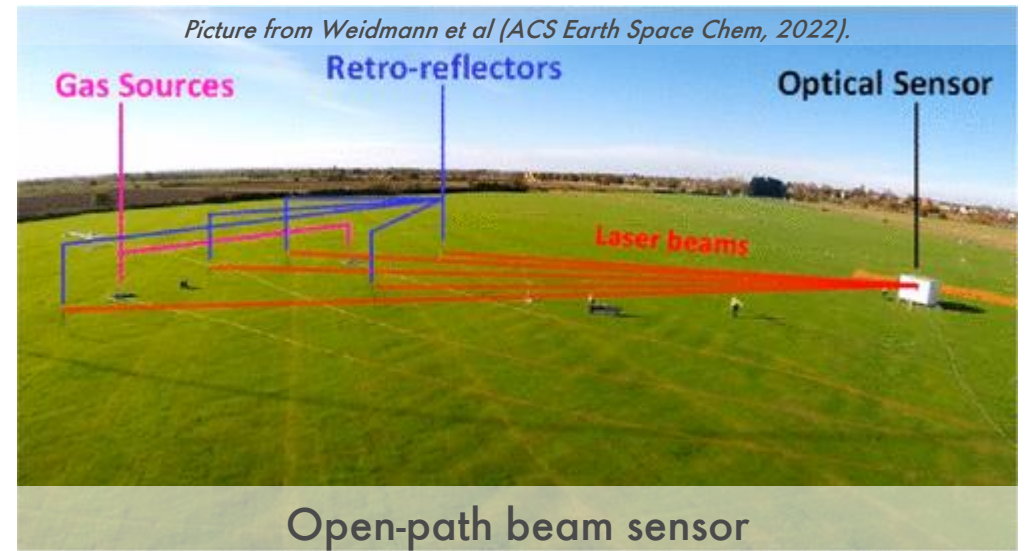
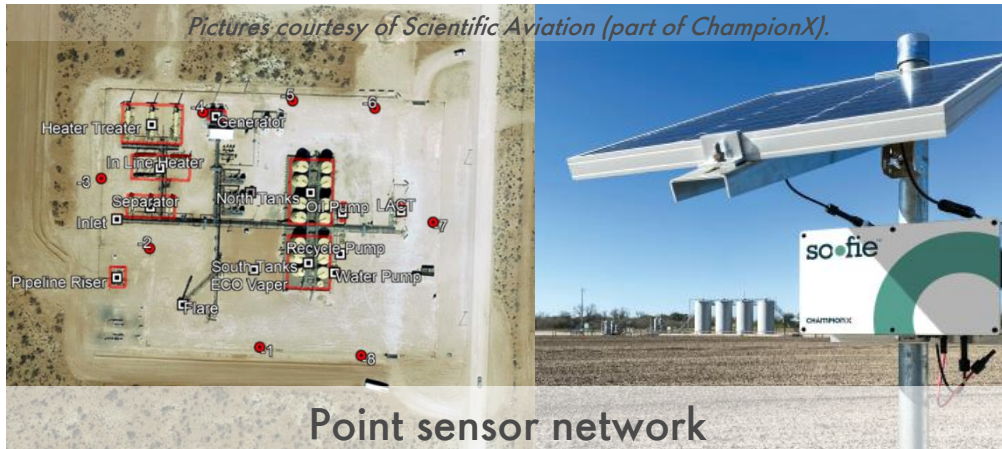


Periodic surveys



Continuous monitoring

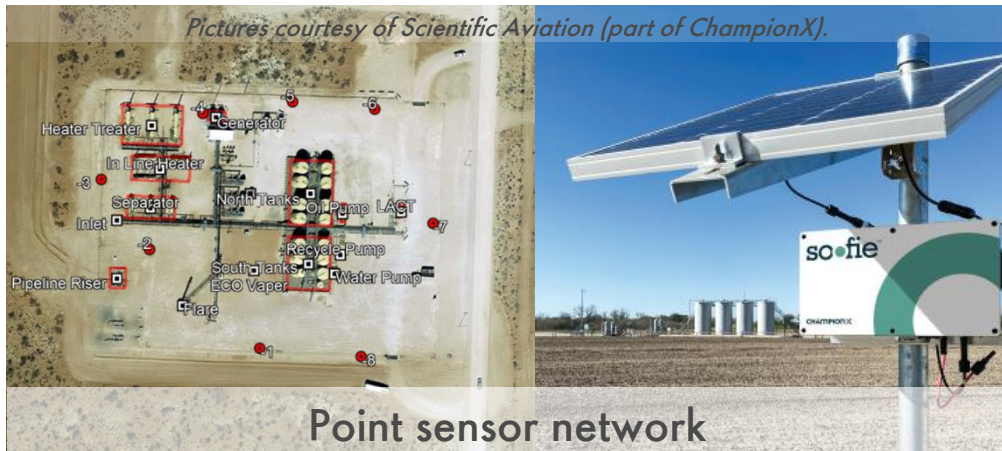
Continuous monitoring technology



Potential benefits of continuous monitoring systems:

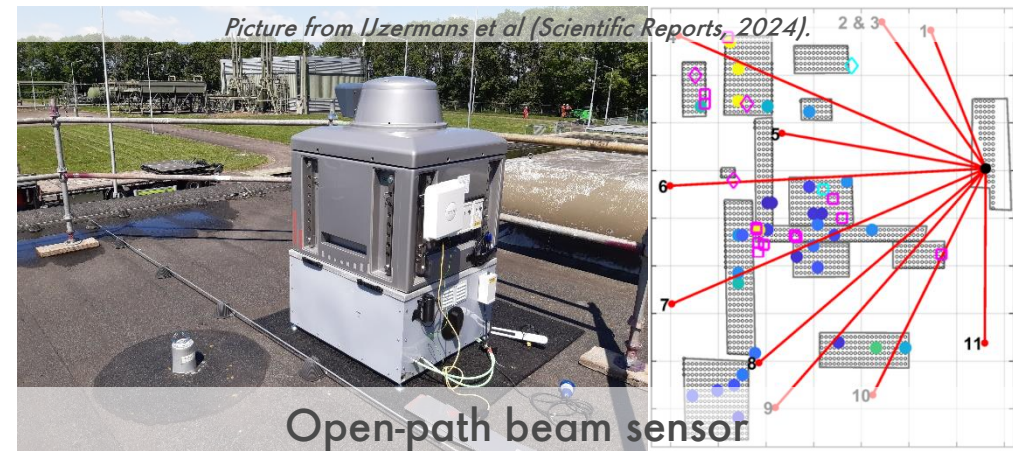
- Early detection of unknown emissions (replacing or supporting Leak Detection and Repair campaigns)
- Quantification of time-varying emissions over long periods of time (continuous site-level measurement for OGMP2.0 L5)
- Demonstration of absence of emissions

Relevance of pyELQ for continuous monitoring technology



Multiple deployments:

- Remote processing facility
- Large manned processing facility
- Well pad during well completion operations
- Data analysis done with pyELQ, in addition to vendor's own methods



Multiple deployments:

- Controlled release tests, in three campaigns
- Long-term deployment at medium-sized manned processing facility
- Data analysis done with pyELQ, results reported in [IJzermans et al \(Scientific Reports, 2024\)](#)

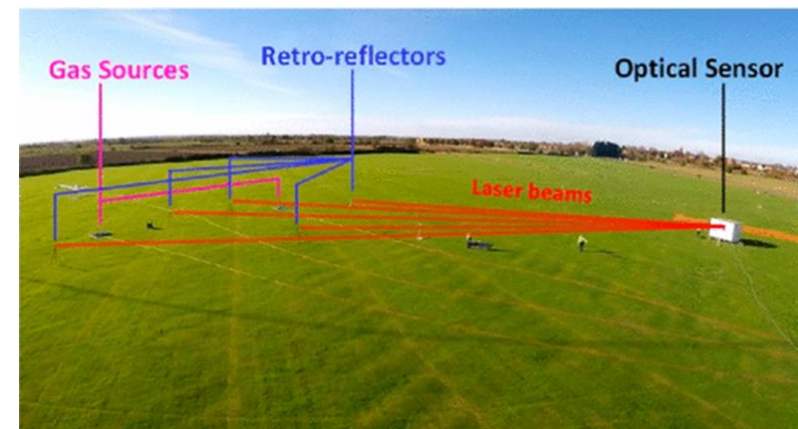
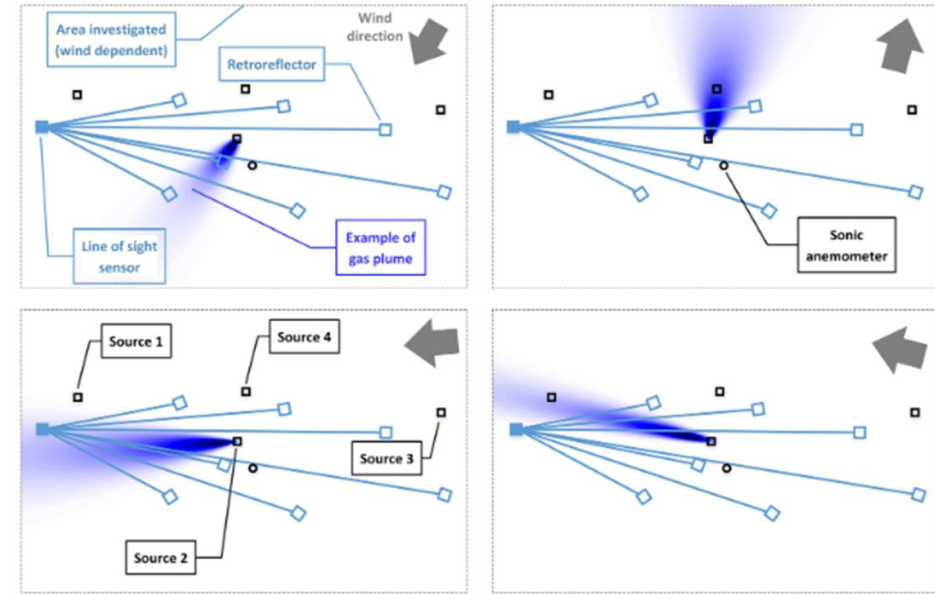


Technical details

The mathematics behind the code

Gaussian plume dispersion modelling

- To do inversion- need a model for mapping emissions at the **source** to concentration measurements at the **sensor**.
- We generally use the **Gaussian plume model**.
- Cross-section of the plume is a Gaussian density.
- Plume widens as it travels downwind, due to turbulent effects in the atmosphere.
- Figures taken from [Hirst et al, 2020](#); [Weidmann et al, 2022](#).



Concentration $c(x, y, z) = s \times a(x, y, z)$

Source emission rate s

Plume coupling coefficient $a(x, y, z) = \frac{1}{2\pi u \sigma_h(x) \sigma_v(x)} \exp\left(-\frac{y^2}{2\sigma_h^2(x)}\right) \left[\exp\left(-\frac{(z-H)^2}{2\sigma_v^2(x)}\right) + \exp\left(-\frac{(z+H)^2}{2\sigma_v^2(x)}\right) \right]$

Wind speed u

Horizontal wind sigma $\sigma_h(x)$

Vertical wind sigma $\sigma_v(x)$

Source height H

Bayesian Inversion

- The observed concentration values are represented using the following model:

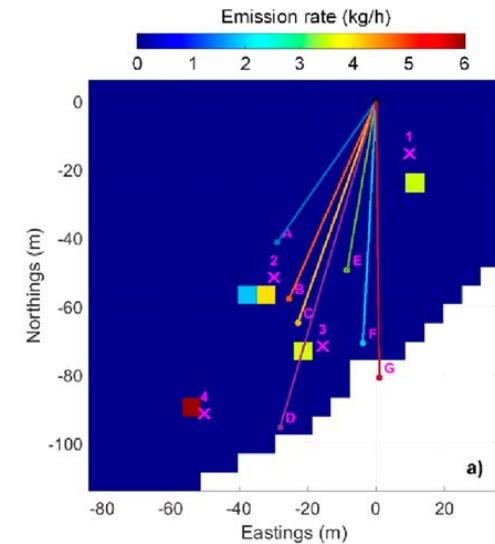
$$\mathbf{y} = \mathbf{A}\mathbf{s} + \mathbf{b} + \boldsymbol{\epsilon}$$

- Components are as follows:
 - $\mathbf{y} = (y_1, y_2, \dots, y_n)'$ is the vector of concentration observations (units: ppm).
 - $\mathbf{A} = (A_{11}, A_{12}, \dots, A_{21}, \dots, A_{ij}, \dots)$ is the matrix of **Gaussian plume coefficients** (units: 1e6 hr/kg)
 - $\mathbf{s} = (s_1, s_2, \dots, s_m)'$ is the vector of **source emission rates** (units: kg/hr).
 - $\mathbf{b} = (b_1, b_2, \dots, b_n)'$ is the vector of **atmospheric background methane** concentrations (units: ppm, typically around 1.9 - 2 ppm).
 - $\boldsymbol{\epsilon} = (\epsilon_1, \epsilon_2, \dots, \epsilon_n)'$ is the vector of **measurement error** terms (units: ppm).
- Main task of the inversion: separate the local "spiky" source contributions from the smooth/slowly-varying background contributions.
- **Bayesian inversion:** **posterior** distribution is product of **likelihood** and **prior** distributions
$$p(\mathbf{s}, \mathbf{b} | \mathbf{y}) \propto p(\mathbf{y} | \mathbf{s}, \mathbf{b}) \times p(\mathbf{s}) \times p(\mathbf{b})$$
- Can't evaluate posterior parameter estimates directly- so we sample from the distribution using **Markov Chain Monte Carlo (MCMC)**.

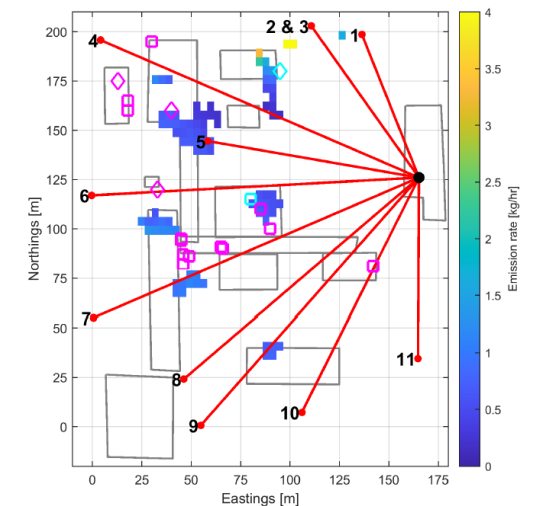
Inversion: source location information

- Two approaches to estimating source location implemented in the code:
 1. Fix source locations (e.g. on a grid at ground level), and switch off sources that don't fit the data well.
 2. Free source map, with locations estimated as part of the MCMC solver.
- In option 2, we use **reversible jump MCMC** to estimate number of sources & location simultaneously:
 - Create a new source in a **random location** (with a randomly-sampled emission rate).
 - Compute the **prediction** for the data with & without the extra source.
 - If adding the new source improves the fit to the data, we **accept** it (on average); otherwise, we **reject**.

[With a similar process for removing sources.]



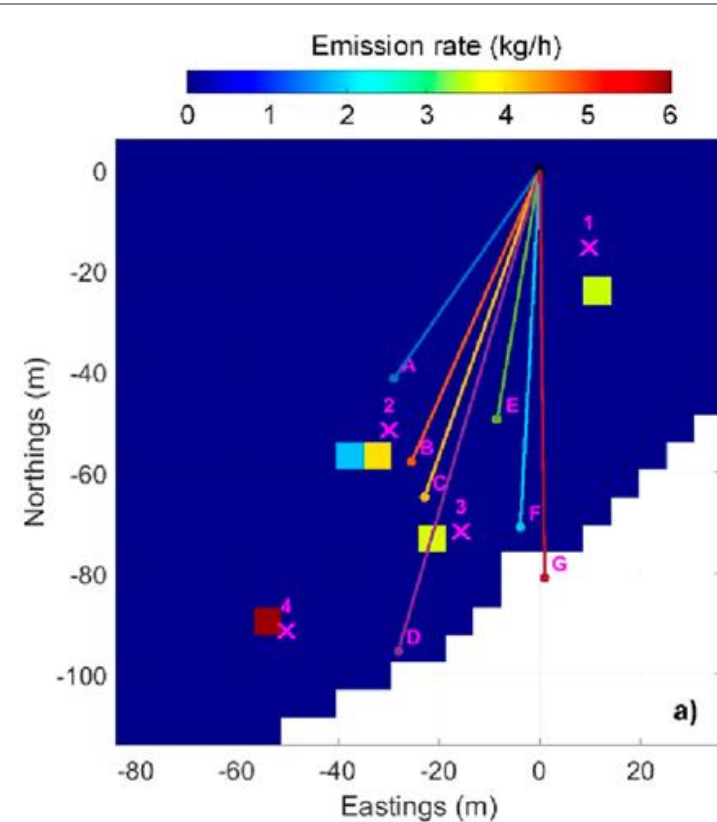
Gridded solution



Free (RJ) solution

Results in controlled release tests: open-path beam sensor

- Test with controlled releases at an empty airfield in the UK, with MIRICO prototype open-path beam sensor ([Weidmann et al \(ACS, 2022\)](#)).
- Four different, but simultaneously emitting methane sources of 3-5 kg/h were successfully detected, located and quantified, without a priori knowledge of number of sources, source location and magnitude – even for sources outside of the area covered by the beams.

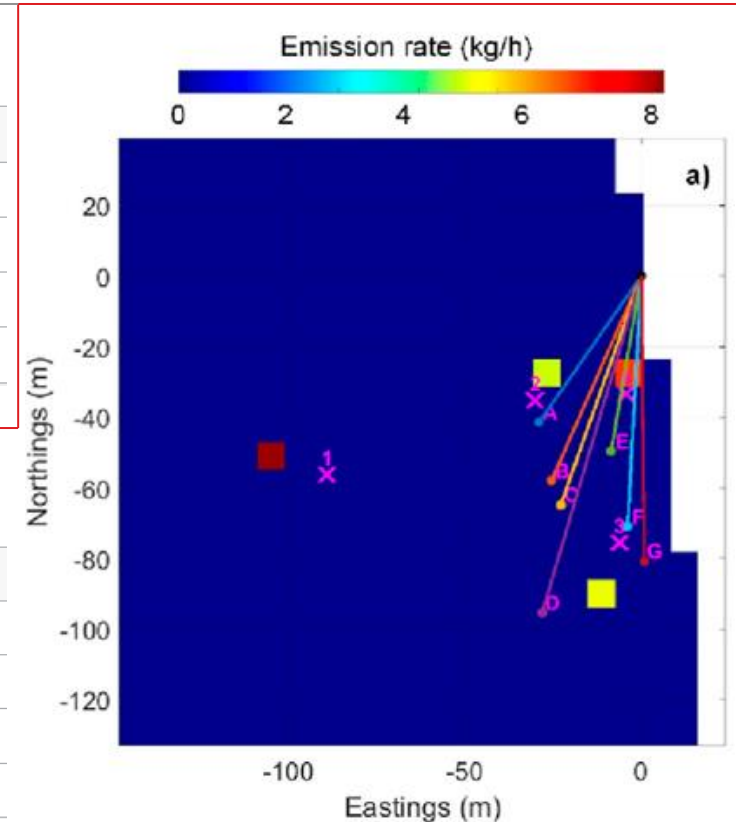


“known-known” case

source	actual rate(kg/h)	inferred rate(kg/h)	inferred to actual relative difference (%)
1	5.11 ± 0.12	3.5 ± 0.5	-31
2	5.03 ± 0.04	5.9 ± 0.9	+17
3	5.06 ± 0.06	3.6 ± 0.3	-29
4	5.06 ± 0.03	6.1 ± 0.5	+20

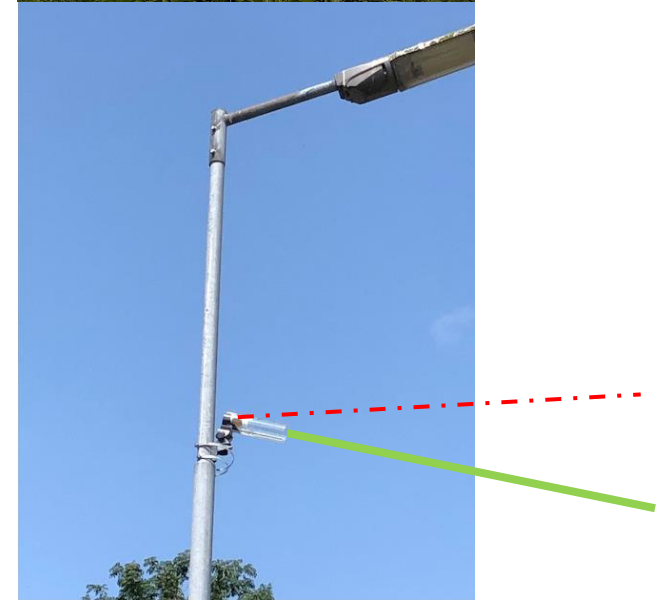
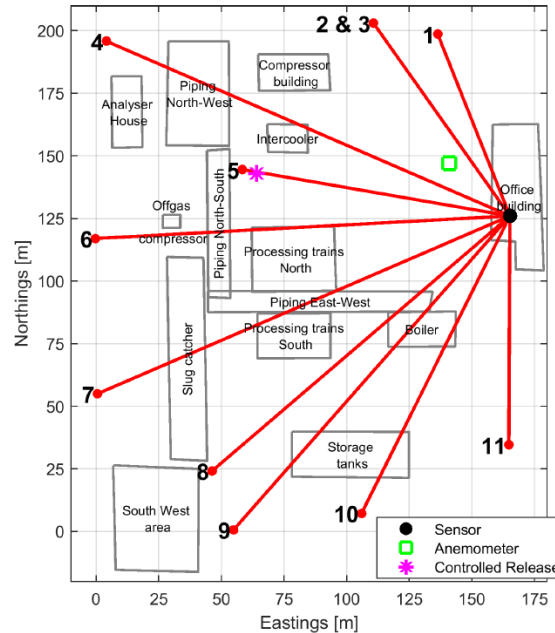
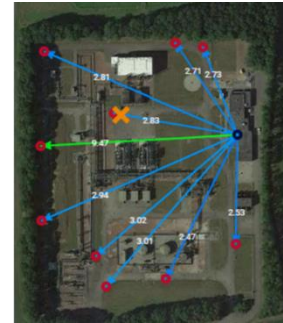
“unknown-unknown” case

source	actual rate (kg/h)	inferred rate (kg/h)	inferred to actual rate relative difference
1	5.03 ± 0.04	8.7 ± 0.7	+73
2	5.03 ± 0.05	5.0 ± 0.3	-1
3	5.02 ± 0.07	5.2 ± 0.4	+4
4	5.04 ± 0.14	7.1 ± 0.5	+41



Test in oil & gas facility: open-path beam sensor (1/2)

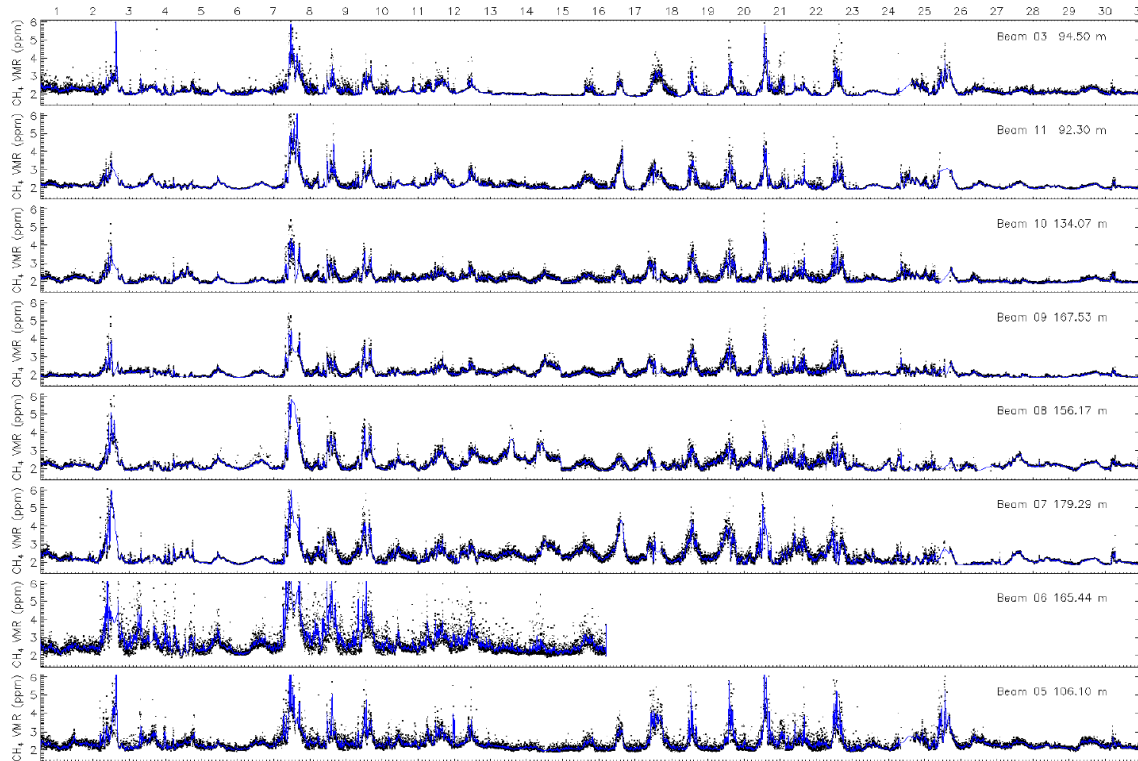
- Test with MIRICO's first commercial open-path beam sensor at a gas compression and distribution facility
- Results reported in [IJzermans et al \(Scientific Reports, 2024\)](#)



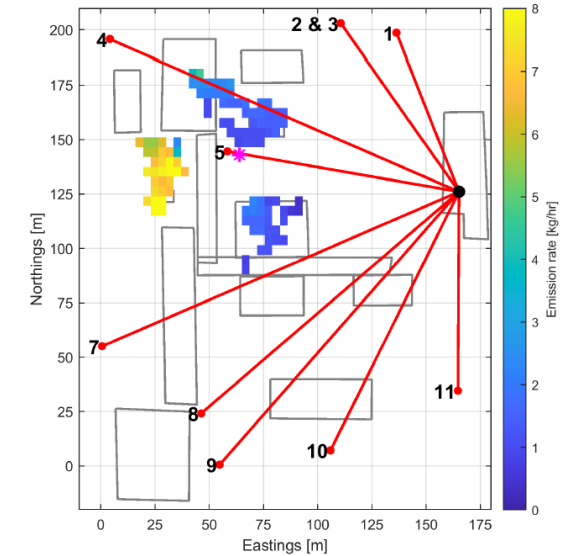
Test in oil & gas facility: open-path beam sensor (2/2)

- Continuous (~2 min frequency) measurement of path-averaged CH₄ concentration along all beams.
- Peaks during the nighttime in background concentrations - probably related to temperature inversion.
- Data analysis performed on suite of short-term controlled releases (4x ~60 minutes).
- Persistent sources identified with data analysis over long time series; confirmed with OGI.

* Release location



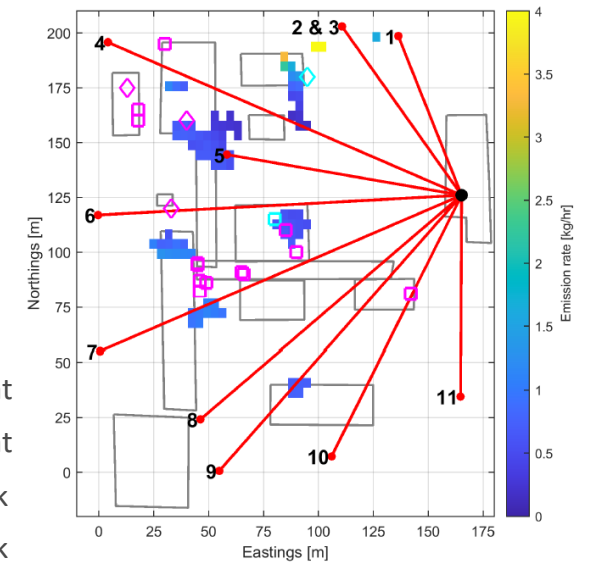
Time series for 1 month of methane concentration measurements.



Controlled release, 5 kg/h.

OGI results:

- ◇ Large vent
- ◇ Small vent
- Large leak
- Small leak



Persistent sources, ~5 kg/h total.



Open-sourcing pyELQ

Open-sourcing pyELQ through LFE

- pyELQ was open-sourced in SEDE Open on 14 February 2024. Link here: <https://github.com/sede-open/pyELQ>
- Motivation (why LFE):
 - Increase awareness of the functionality outside of Shell
 - Encourage collaboration with others working in the industry
 - Facilitating continuous improvement in the capabilities available for methane emissions quantification
 - Help to create transparency around approaches to methane emissions quantification
 - Potential value of these algorithms is “bigger” when open sourced

Code quality

- All code on Github: <https://github.com/sede-open/pyELQ>
- pyproject.toml
- PEP 8 coding standard with (automated) tools black and isort
- Docstrings in Google format, including typehinting
- Github actions: automate workflows, PR templates
- SonarQube, Mend, Github Advanced Security
- GH pages: <https://sede-open.github.io/pyELQ/>
- Packaging and upload to PyPi: <https://pypi.org/project/pyelq-sdk/>

Q&A



Back-up slides

Potential improvements to the code base

Allow combining fixed and variable source locations within the same solution (<i>New features/models</i>).	Allows users to specify fixed locations for known sources at a site, and then allow a free source map to fit any unknown source locations.
Implement options in the openMCMC back end for using jax.numpy package for calculations (<i>Improvements to existing functionality</i>).	JAX is a python package that can auto-generate gradients for functions (without them having to be implemented separately) and allows compilation of functions to give potential substantial speed-ups. Implementing JAX options for some of the functions (e.g. Gaussian plume, normal distribution) will give extra functionality, and reduce implementation time for other functionality that we want to add in future- for example: <ul style="list-style-type: none">• Gradient-based sampling for source location (enables better source location sampling, less likely to get stuck).• Gradient-based sampling of plume dispersion parameters.• Maximum likelihood initialization routines.
Dispersion modelling with obstacles in the flow field (<i>New features/models</i>)	Add an extra dispersion model to the code- better able to handle non-constant wind directions, and to handle obstacles (e.g. buildings) in the flow field.

